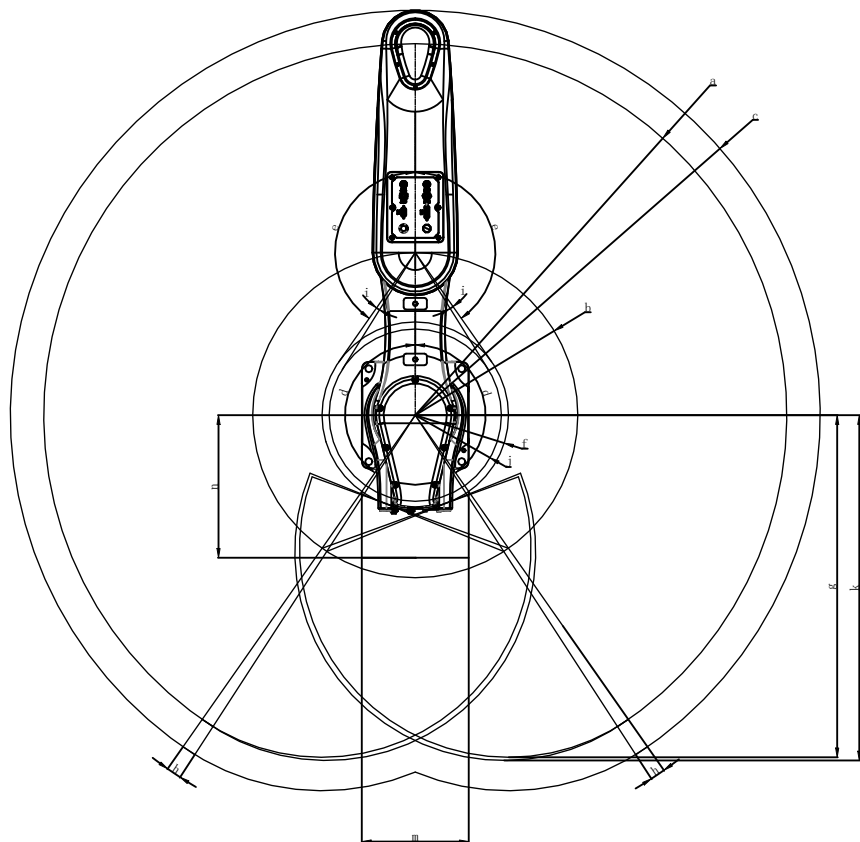
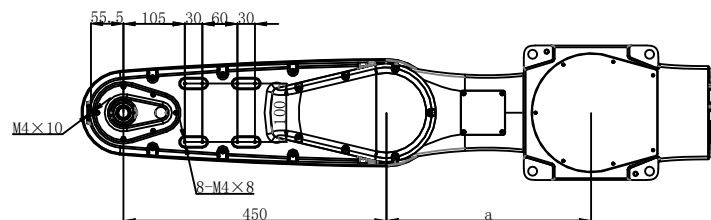
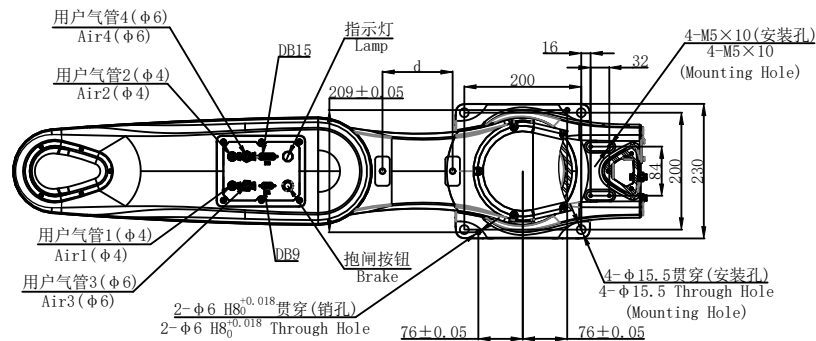


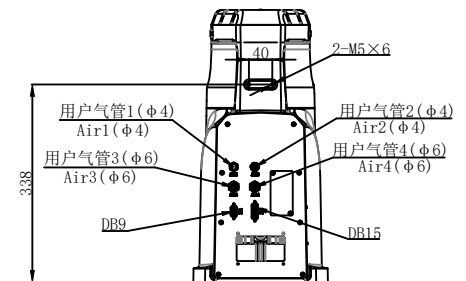
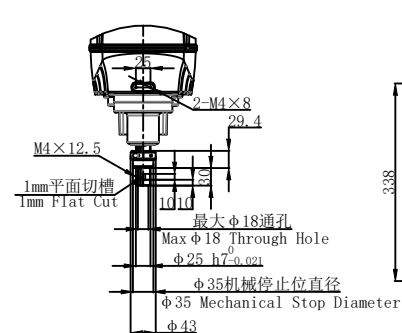
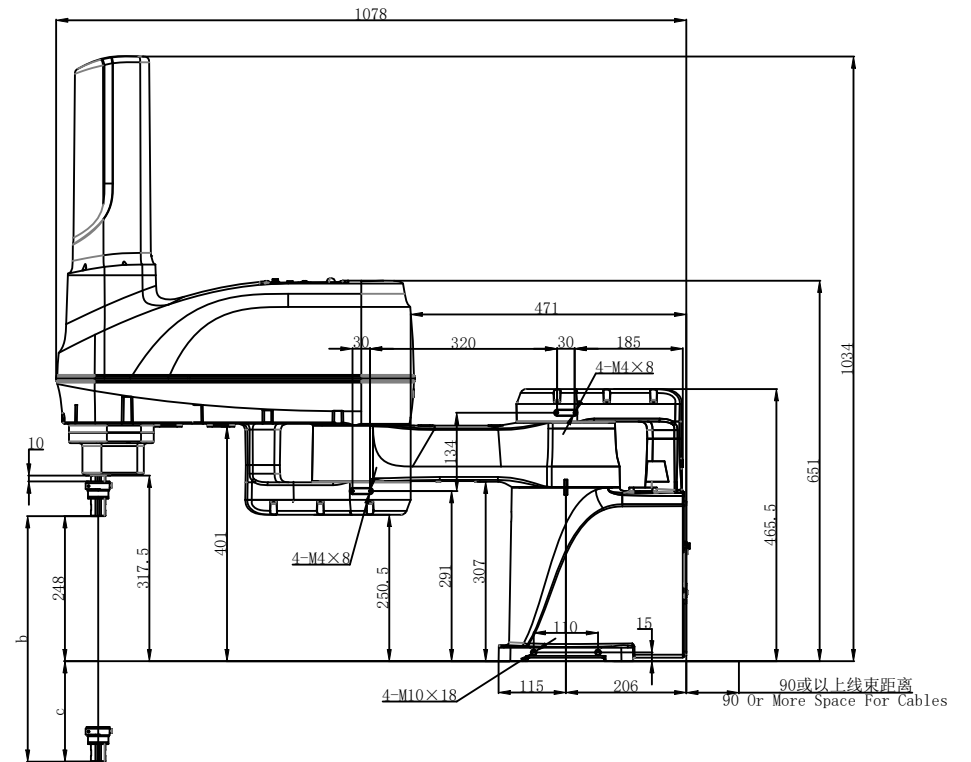
底部安装面
Base Datum Plane

ESR20 series range of motion parameters for different arm lengths				
机型名称	ESR20-800Z30	ESR20-800Z42	ESR20-1000Z30	ESR20-1000Z42
The name of the model				
a. 第1轴臂长+第2轴臂长 (mm)	800	800	1000	1000
a. 1st axis arm length+2st axis arm length (mm)				
b. 第1轴臂长 (mm)	350	350	550	550
b. 1st axis arm length (mm)				
c. 最大运动范围 (mm)	872	872	1072	1072
c. Maximum range of motion (mm)				
d. 第1关节运动范围 (°)	145			
d. Range of motion of the 1st joint (°)				
e. 第2关节运动范围 (°)	145			
e. Range of motion of the 2st joint (°)				
f. 运动范围	201	201	315.5	315.5
f. Range of motion				
g. 后方运动范围	737	737	901	901
g. Rear range of motion				
h. 第1关节机械停止位的角度 (°)	2			
h. The angle of the mechanical stop position of the 1st joint (°)				
i. 第2关节机械停止位的角度 (°)	3			
i. The angle of the mechanical stop position of the 2st joint (°)				
j. 机械停止位的范围	185.5	185.5	292	292
j. The range of mechanical stop bits				
k. 后方机械停止位的范围	744	744	911	911
k. The range of the rear mechanical stop bits				
m. 运动范围	230.5	230.5	362	362
m. Range of motion				
n. 运动范围	307			
n. Range of motion				
p. 第3关节运动范围 (mm)	300	420	300	420
p. Range of motion of the 3th joint (mm)				
q. 至底座安装面的距离 (mm)	52	172	52	172
q. Distance to the mounting surface of the base (mm)				
r. 第3关节行程余量 (mm)	2			
r. Stroke margin of the 3th joint (mm)				

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比例 Scale	1:1	页码 Page	
		运动范围图 Robot Workspace	
修订记录 Revision Record		ESR20-800Z42	



ESR20系列不同臂长机型参数 ESR20 series with different arm lengths				
机型名称 The name of the model	ESR20-800Z30	ESR20-800Z42	ESR20-1000Z30	ESR20-1000Z42
a	350	350	550	550
b	300	420	300	420
c	52	172	52	172
d	120	120	220	220



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比例 Scale	1:1	页码 Page	
		主要安装尺寸图 Main Dimensions	
修订记录 Revision Record		ESR20-800Z42	