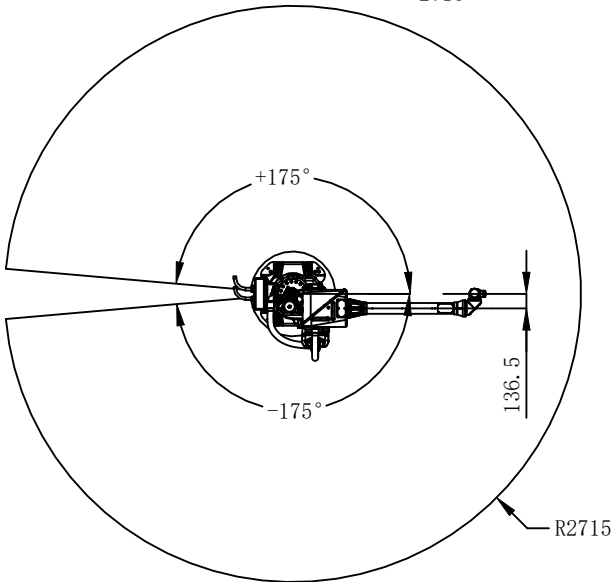
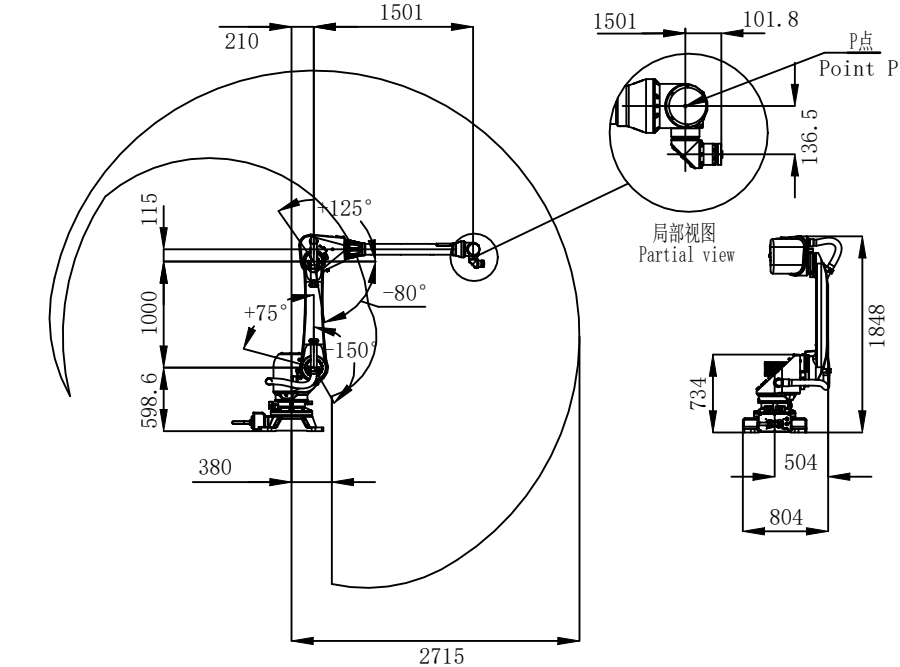
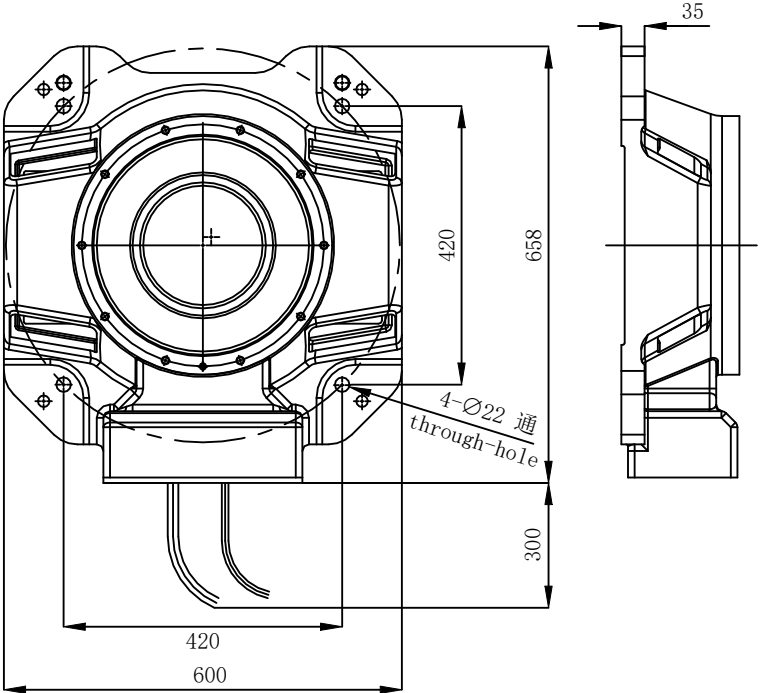


P点运动范围图  
Point P locus



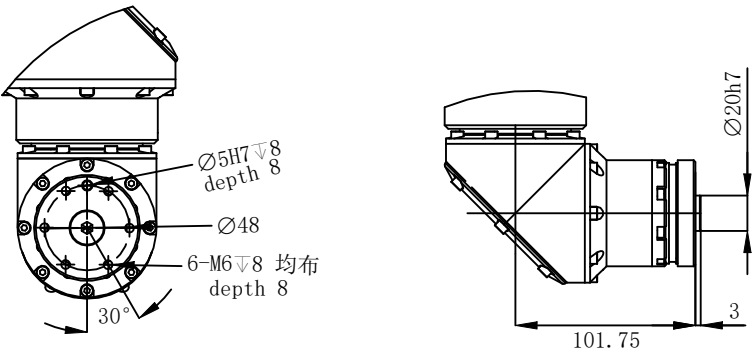
底座安装尺寸图

Installation dimension drawing of base



手腕及末端安装尺寸图

Wrist and end mounting dimension drawing



|          |                                   |
|----------|-----------------------------------|
| B        |                                   |
| 零件代号     | Part code                         |
| 借(通)用件登记 | Adopted/General part registration |
| 描图       | Drawing                           |
| 描校       | Drawing correction                |
| 旧底图总号    | Old base map total number         |
| 底图总号     | Base map total number             |
| 签字       | Signature                         |
| 日期       | Date                              |

|                |              |                 |                             |                 |            |  |                                                       |  |            |                  |             |                                                |  |  |  |  |
|----------------|--------------|-----------------|-----------------------------|-----------------|------------|--|-------------------------------------------------------|--|------------|------------------|-------------|------------------------------------------------|--|--|--|--|
|                |              |                 |                             |                 |            |  | 埃夫特智能装备股份有限公司<br>EFORT Intelligent Equipment Co., Ltd |  |            |                  |             |                                                |  |  |  |  |
|                |              |                 |                             |                 |            |  |                                                       |  |            |                  |             |                                                |  |  |  |  |
|                |              |                 |                             |                 |            |  |                                                       |  |            |                  |             |                                                |  |  |  |  |
|                |              |                 |                             |                 |            |  |                                                       |  |            |                  |             |                                                |  |  |  |  |
| 标记<br>Sign     | 处数<br>Number | 分区<br>Partition | 更改文件号<br>Change file number | 签字<br>Signature | 日期<br>Date |  | 图样标记<br>Pattern marker                                |  |            | 重量(Kg)<br>Weight | 比例<br>Scale | 运 动 范 围 图<br>Robot workspace<br><br>GR680-2700 |  |  |  |  |
| 设计<br>Design   |              |                 | 标准化<br>Standardization      |                 |            |  |                                                       |  |            |                  |             |                                                |  |  |  |  |
|                |              |                 |                             |                 |            |  |                                                       |  |            |                  |             |                                                |  |  |  |  |
| 审核<br>Review   |              |                 |                             |                 |            |  |                                                       |  |            |                  |             |                                                |  |  |  |  |
| 批准<br>Approval |              |                 |                             |                 |            |  | 图幅<br>Sheet                                           |  | 共<br>Total | 页<br>page        | 第 页<br>Page |                                                |  |  |  |  |