# **EFORT**

# **ESR3-400Z15**

### ESR3-400Z15,

Maxium payload 3 kg with maxium reach 400 mm.

#### Highlights

 High rhythm and high precision
 The fastest standard cycle time can reach 0.33 s, and the robot positioning accuracy can reach 0.01 mm.

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2. High rigidity and low vibration
Robot body mode and rigidity enhancement, combined with vibration suppression and active vibration suppression functions, effectively reduce vibration.

3. Easy to maintain and scalable
The detachable structure of cables and batteries allows for the replacement of robots inside the device, and the built-in camera network cable enables various communication extensions.

Applications

It can be used in handling, sorting, assembly, etc.

Industries

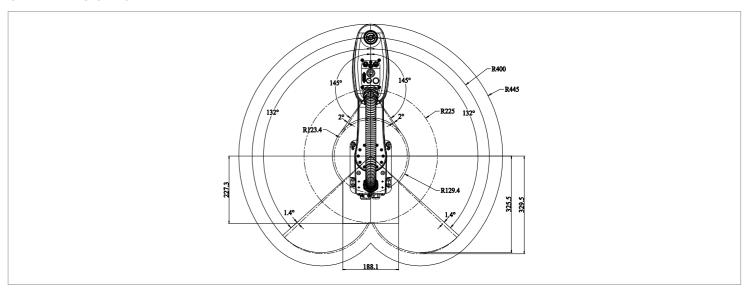
Suitable for industries such as 3C electronics, lithium batteries, automotive electronics, and photovoltaics.



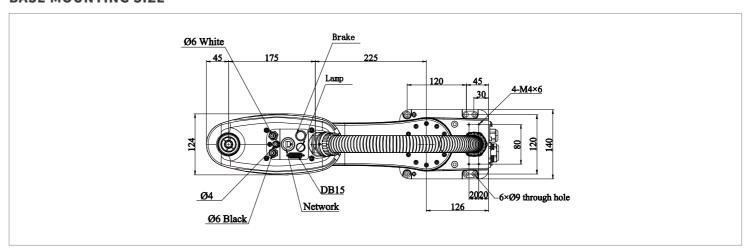


Model Reach		ESR3-400Z15
		400 mm
Max. payload on wrist	Rated	1 kg
	Maximum	3 kg
Robot weight		12 kg
Maximum speed	J1+J2	7200 mm/sec
	J3	1100 mm/sec
	J4	3000°/sec
Motion range	J1	±132°
	J2	±145°
	J3	150 mm
	J4	±360°
Repeatability	J1+J2	±0.01 mm
	J3	±0.01 mm
	J4	±0.01°
Standard cycle time		0.33 s
J4 allowable moment of inertia	Rated	0.005 kg·m²
	Maximum	0.05 kg·m²
<b>Electric lines</b>		D-Sub 15-Pin
Pneumatic lines		φ4 mmx1,φ6 mmx2
J3 downward force		100 N
Installation		Floor
Installation enviroment	Ambient temperature	5~40°C
	Ambient humidity	RH≤80% (No dew nor frost allowed)

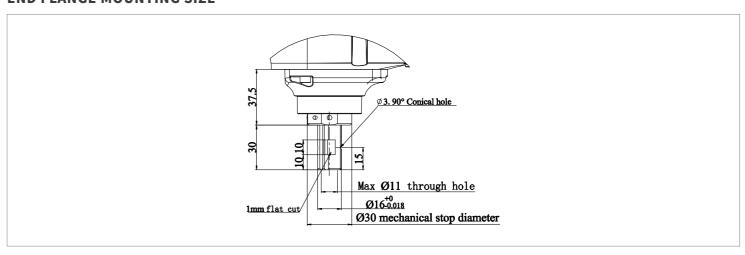
# **OPERATING SPACE**



## **BASE MOUNTING SIZE**



# **END FLANGE MOUNTING SIZE**



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PHONE: (00 86) 400-052-8877 ADDRESS: No.96 East Wanchun Road, China(Anhui) Pilot Free Trade Zone Wuhu Area, Wuhu, Anhui Province, China WWW.EFORT.COM.CN