# ER70-1900



## ER70-1900,

Maxium payload 70 kg with maxium reach 1901 mm.

## ■ Highlights

Thanks to the high stiffness structure, with high-speed intelligent palletizing application software, the takt is improved by 20%, bring customers more efficiency:

Multiple specific application software could be integrated, with soft PLC and a variety of field bus interface, which enable customers easily face various application challenges;

High performance collision detection function helps safety realization.

#### Applications

It can be used in grinding, polishing, handling operations, palletizing, etc.

## Industries

Suitable for auto parts, photovoltaic, food and beverage, building materials, logistics and warehousing and other industries.



## EFORT INTELLIGENT EQUIPMENT CO.,LTD.

PHONE: (00 86) 400-052-8877

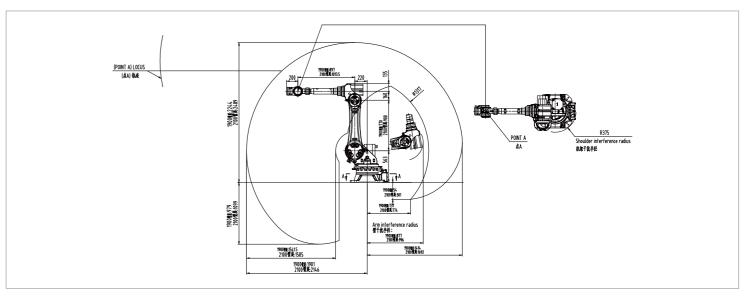
ADDRESS: No.96 East Wanchun Road, China(Anhui) Pilot
Free Trade Zone Wuhu Area, Wuhu, Anhui Province, China
WWW.EFORT.COM.CN

## **SPECIFICATIONS**

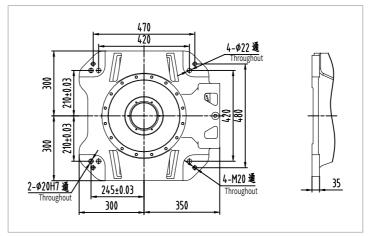
| Model                      |                        | ER70-1900                         |
|----------------------------|------------------------|-----------------------------------|
| Туре                       |                        | Articulated                       |
| Controlled axes            |                        | 6 Axes                            |
| Max. payload on wrist      |                        | 70 kg                             |
| Repeatability              |                        | ±0.06 mm                          |
| Robot weight               |                        | 545 kg                            |
| Reach                      |                        | 1901 mm                           |
| Robot IP grade             |                        | IP54/IP67 (Wrist)                 |
| Cabinet IP grade           |                        | IP54                              |
| Drive mode                 |                        | AC servo drive                    |
| Installation               |                        | Floor                             |
| Installation<br>enviroment | Ambient<br>temperature | 0~45 °C                           |
|                            | Ambient<br>humidity    | RH≤80% (No dew nor frost allowed) |
|                            | Vibration acceleration | 4.9 m/s <sup>2</sup> (<0.5 G)     |

| Allowable load<br>moment at wrist | J 4 | 182 N·m     |
|-----------------------------------|-----|-------------|
|                                   | J 5 | 182 N·m     |
|                                   | J6  | 120 N·m     |
| Allowable load inertia at wrist   | J 4 | 12.68 kg·m² |
|                                   | J 5 | 12.68 kg·m² |
|                                   | J6  | 10 kg·m²    |
| Maximum speed                     | J1  | 210°/sec    |
|                                   | J2  | 160°/sec    |
|                                   | J3  | 190°/sec    |
|                                   | J 4 | 310°/sec    |
|                                   | J 5 | 270°/sec    |
|                                   | J6  | 400°/sec    |
| Motion range                      | J1  | ±180°       |
|                                   | J2  | +70°/-130°  |
|                                   | J3  | +175°/-80°  |
|                                   | J 4 | ±360°       |
|                                   | J 5 | ±115°       |
|                                   | J6  | ±450°       |
|                                   |     |             |

## **OPERATING SPACE**



## **BASE MOUNTING SIZE**



## **END FLANGE MOUNTING SIZE**

